

European Journal of
Technology
(EJT)



Drilling Optimization and ROP Prediction with Hybrid ML Models

Pankaj Verma, Krishna Gandhi

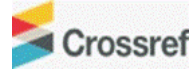


Drilling Optimization and ROP Prediction with Hybrid ML Models

 Pankaj Verma,  Krishna Gandhi

¹Indian Institute of Management, Bangalore (IIM-Bangalore), Bannerghatta Road, Bengaluru, Karnataka, India

²Illinois State University, 100 N University St, Normal, IL 61761, United State



Article history

Submitted 04.12.2024 Revised Version Received 02.01.2024 Accepted 05.02.2024

Abstract

Purpose: The complexity of drilling activities has been enhanced by deeper wells, the heterogeneous formations, and the need to provide cost-effective and time-saving hydrocarbon production. One of the most important parameters of drilling performance is rate of Penetration (ROP), which has a direct impact on the efficiency of operations, non-productive time (NPT), and costs. The traditional mechanistic and empirical ROP models that had been important in the past are not very useful in nonlinear interaction, dynamic drilling conditions, and heterogeneous lithologies. However, existing reviews lack a structured problem statement that clearly identifies the limitations of standalone ML and classical ROP models under dynamic drilling conditions and the need for hybrid frameworks that improve accuracy, robustness, and real-time applicability. This review addresses this gap by systematically analyzing hybrid ML approaches and their role in drilling optimization.

Materials and Methods: Improved drilling optimization through machine learning (ML) methods, especially hybrid ML models, has redefined the future of drilling optimization, which unites the advantages of various predictive models to improve accuracy, strength, and generalization. This review is a synthesis of literature on hybrid ML

applications in ROP prediction, which is divided into three categories: optimization-integrated, ensemble, soft computing, and physics-informed models. Their methodologies, data requirements, real-time integration, operational problems, and performance in comparison to standalone ML models are addressed in the paper.

Findings: The essential restrictions, including data quality, computing aspects, and the problem of interpretability, are identified, and the future research direction is also outlined. The synthesis offers an organized scheme of comprehending the development of hybrid ML models in the drilling optimization and outlines opportunities of future progress within the limitations of technologies.

Unique contribution to theory, practice and policy: Improved drilling optimization through machine learning (ML) methods, especially hybrid ML models, has redefined the future of drilling optimization, which unites the advantages of various predictive models to improve accuracy, strength, and generalization.

Keywords: *Drilling Optimization, Rate of Penetration (ROP) Hybrid Machine Learning, Physics-Informed ML, Real-Time Drilling*

INTRODUCTION

Drilling operations undergo tremendous changes due to the incessant need of hydrocarbons, the complex reservoirs, and the constant move towards deeper and more technical wells[1]. When wells are drilled into high pressure and high temperature (HPHT) environments, and non-traditional formations, the drilling difficulties manifested in low rate of penetration (ROP), excessive vibration, inadequate bit choice and lithological variability are exacerbated [2]. These complexities have increased the desire to have efficient drilling optimization strategies that will help to reduce non-productive time (NPT) to minimize operational risks and improve overall drilling efficiency. Optimization of drilling has thus become a major field of focus in the petroleum engineering sector with multidisciplinary intervention that aims at enhancing the performance of the drilling process with minimal cost and time.

The ROP is one of the most important and significant indicators that are used to determine drilling performance [3]. ROP is a direct measure of the drilling efficiency since it establishes the speed at which a well will reach the target depth. An increased ROP will have the effect of decreasing the duration of the drilling process, this will further decrease the cost of rigs, less geological uncertainties, and enhance the rigs operational safety. On the other hand, reduced ROP may cause very high NPT, long bit life, and increased variations in the risk of differential sticking, formation instability, and unplanned events. Due to the economic and operational consequences of ROP, there has been a long time when the petroleum industry has been interested in accurate predictability and efficiency of ROP in different geological and operational settings. This has placed ROP prediction models as a fundamental element of current drilling optimization processes.

Machine Learning (ML) methods were also embraced by the petroleum engineering community as the means of making drilling decisions and increasing the accuracy of ROP prediction [4]. The nonlinear, dynamic and multivariate nature of drilling systems tended to be hard to explain by the traditional methods like analytical or physics-based models. ML algorithms such as Artificial Neural Networks (ANNs), Support Vector Machines (SVM), and Random Forests (RF) as well as Fuzzy Logic, Genetic Algorithms (GA) and other evolutionary computation algorithms proved to be viable options that can be used to learn complex relationships with real-time drilling information.

Figure 1 shows that the adoption of ML in the drilling processes is accelerating, and it marks the key milestones of the use of intelligent data-driven approaches to the optimization of drilling operations and ROP forecasting.

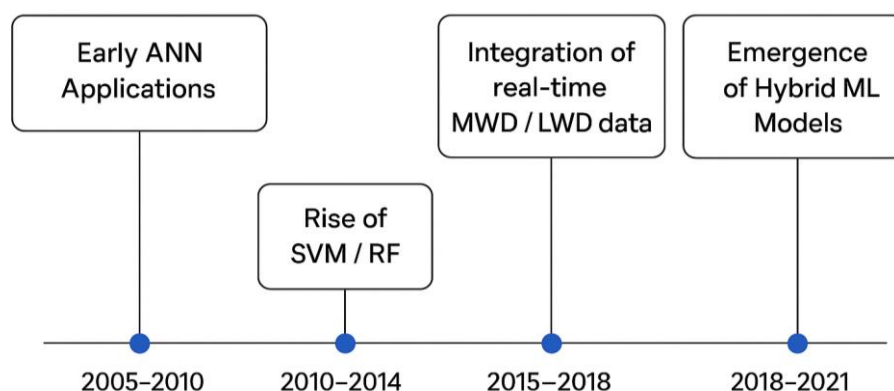


Figure 1: Timeline of ML Adoption in Drilling

This review is limited to hybrid ML models that are trained in the field of drilling optimization and ROP prediction. The synthesis of methodologies, datasets, model structures, and comparative performance of hybrid models presented in this paper offers a systematic frame of reference under which their development can be examined and existing research gaps that preceded the pervasive introduction of advanced deep learning and real-time automation systems can be identified. This study adopts a systematic literature review methodology, analyzing peer-reviewed journal articles and conference papers focused on ROP prediction and drilling optimization using hybrid ML models. Studies were categorized based on model type, data sources, optimization strategy, and real-time applicability.

Fundamentals of Drilling Operations and ROP

Knowledge of the basics of drilling processes and classical models of ROP is the key to understanding the transition to machine learning and hybrid methodology. The factors affecting the rate of penetration (ROP) are mechanical, hydraulic, bit-related, and geological factors, interacting in non-linear and complex manners [5]. Classical ROP models had a high-early predictive capability, but were limited by simplifications and assumptions and were only effective in deeper and heterogeneous formations. In this section, drilling mechanics, classical ROP models before ML and limitations of these are reviewed and supported by tables and figures at appropriate points.

Fundamentals of Drilling Mechanics.

Well construction and ROP prediction are based on drilling mechanics. Comprehending these parameters can enable the engineers to maximize the efficiency of drilling, minimize the bit wear, and non-productive time [6].

A. Weight on Bit (WOB)

WOB is the force applied to the axis to cause rock penetration. It is important to optimize WOB; excessively low achieves low ROP whereas excessively high causes bit damage, excessive torque or stick-slip vibrations that wear out the drillstring.

1. Rotary Speed (RPM)

RPM causes variation in the rate at which the bit turns, and this influences rock breakage. The high RPM tends to raise ROP in soft formations but may hasten the wear or lead to the vibrations of hard lithologies [7]. The best RPM is based on the type of formation and the design of bits.

2. Torque

Torque is used to denote resistance to rotation that the bit faces. High torque can tell about hard formations, bit balling, or ineffective cleaning of holes. The trends of the torque give information about formation changes, drilling efficiency, and mechanical problems.

3. Hydraulics and Mud Flow Rate

The hydraulic energy is also required to carry the cuttings to the surface, cool the bit and stabilize the wellbore. Even in case mechanical parameters are optimized, poor hole cleaning may significantly lower ROP. The important variables are pump rate, density of the mud, nozzle setting and annular velocity.

4. Bit Type and Cutter Design

Bit choice has an impact on rock fragmentation, durability and the ROP that can be attained. PDC bits deliver high ROP in homogeneous formation, roller-cone bits deliver better in

abrasive formations, and hybrid bits are trying to combine the benefits of both. Long term penetration rates are affected by bit wear, cutter geometry or bearing performance.

B. Traditional ROP Equations

Classical ROP models tried to measure the correlation between drilling parameters and drilling rate with simple empirical equations or physics equations in a simplified manner.

1. Bourgoyne & Young (B&Y) Model

The B&Y model is an 8-parameter empirical model which incorporates the WOB, RPM, bit wear, hydraulic effects, formation pressure and drillability. It is flexible and needs sensitive calibration and assumes log-linear input-ROP associations [8].

2. Bingham Model

The Bingham model is an expression of ROP as a linear relation of WOB and bit diameter. It is easy to implement, and only works in shallow or homogeneous geologic formations, and does not consider dynamic changes in the drilling conditions [9].

3. Gates & Taylor (G&T) Model

The model G&T takes into consideration bit wear with time, which predicts the reduction of ROP in abrasive structures. It is also applicable especially in long drilling periods where bit wear has a serious impact on the performance.

Table 1: Comparison of Traditional ROP Models

Model	Key Inputs	Assumptions	Strengths	Limitations
Bourgoyne & Young (B&Y)	WOB, RPM, pore pressure, bit wear, hydraulics, drillability	Log-linear relationships	Comprehensive; widely used	Requires heavy calibration; limited generalization
Bingham Model	WOB, bit diameter	Linear relationship	Simple, fast	Oversimplified; inaccurate for complex formations
Gates & Taylor (G&T)	Bit wear, formation abrasiveness, time	Wear-dependent ROP decline	Good for abrasive formations	Poor real-time capability; limited parameters

C. Limitations of Conventional ROP Models

Despite their historical significance, classical models have several drawbacks [10]:

1. Simplified Mathematical Assumptions

Linear or log-linear assumptions fail to capture the true nonlinear interactions between WOB, RPM, hydraulics, bit wear, and formation properties.

2. Limited Generalization Across Wells and Formations

Models require well-specific calibration. Their accuracy declines sharply when applied to new wells, different lithologies, or dynamic drilling conditions.

3. Inability to Handle Real-Time Dynamics

ROP is influenced by lithological changes, bit wear, hole cleaning efficiency, and mechanical vibrations. Classical models cannot adapt to such variations in real time.

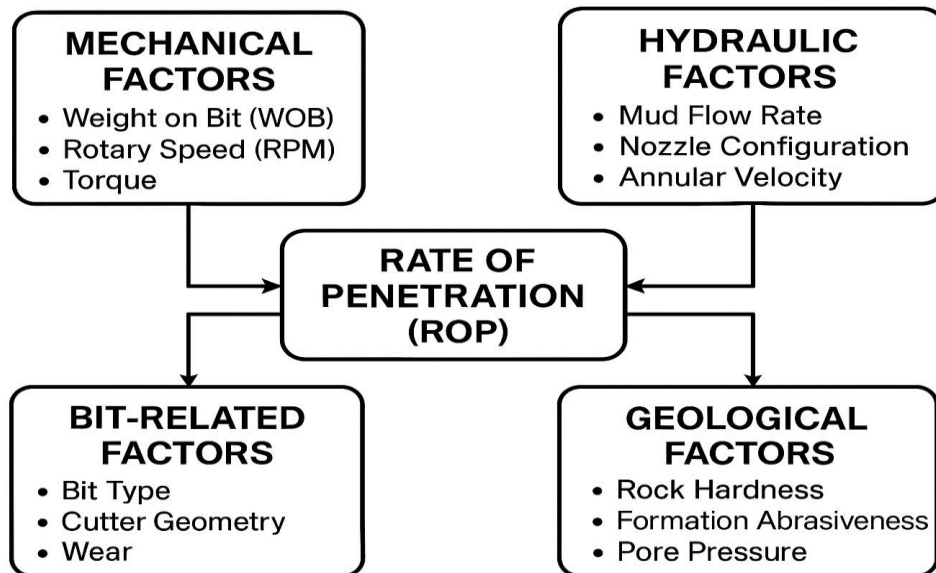


Figure 2: Schematic of ROP Influencing Factors

Figure 2 shows the aspects of ROP that are affected: the mechanical parameters, i.e. WOB, RPM and the torque directly influence bit penetration. Cuttings removal and bit cooling depend on hydraulic factors such as the rate of mud flow, nozzle design and annular velocity. Cutting efficiency is dependent on bit related factors, such as bit type, cutter geometry, and wear, whereas natural limits against penetration are set by geological factors, such as rock hardness, formation abrasiveness, and pore pressure. All these factors demonstrate how difficult it is to predict the ROP.

Foundations of Machine Learning in Drilling

The success of machine learning (ML) application to drilling activities represented a radical change of the traditional mechanistic and empirical paradigm to predictive methods. ML models were also able to deal with nonlinear, interacting variables, and heterogeneous data to enhance the quality of ROP forecasting and the overall drilling optimization. Here, the general categories of the most popular ML algorithms, data preprocessing techniques, and metrics are presented [11].

A. Overview of ML Algorithms Used

There is a range of ML algorithms that were extensively used in drilling optimization and ROP prediction. These algorithms were chosen due to the capacity to reveal the nonlinear patterns, generalization across datasets and real-time prediction or near real-time prediction.

1. Artificial Neural Networks (ANN)

The role of ANNs is based on the human brain structure, which is composed of a series of layers connected by nodes (neurons) capable of learning complicated nonlinearity. ANNs were also popularly applied in the prediction of ROP with respect to the inputs, which included WOB, RPM, torque, bit type, and formation properties. Their capability to predict patterns based on historical data sets made them especially valuable with heterogeneous formations

especially when trained on large amounts of data, but generally vulnerable to overfitting unless overfitting was closely guarded [12].

2. Support Vector Machines (SVM)

The regression or classification of input data in a high-dimensional space and the locating a good hyperplane between classes or a continuous forecasting outcome is the work of SVMs. In ROP studies, SVMs were used to make predictions of high/low penetration rate regimes or classify lithology zones. They can handle smaller datasets with ease, but are likely to be computationally expensive when working with large, multi-variable datasets.

3. Decision Trees (DT) and Random Forests (RF)

Decision Trees divide the data into branches with hierarchies as a result of the features to arrive at predictions. RFs are better than DTs because they are able to combine multiple trees to decrease overfitting and increase predictive stability [13]. These models were extensively applied to determine the key drilling parameters affecting ROP, as well as to process heterogeneous data sets that have nonlinear interactions between WOB, RPM, hydraulics and geological parameters.

4. Gradient Boosting Machines (GBM)

GBMs build on a series of weak learners in order to enhance predictive accuracy. They were especially handy in modeling continuous ROP data in complicated drilling conditions, and of the subtle changes in drilling behavior which might be overlooked by simpler models. Nonetheless, they were prone to noisy data and had to be carefully hyperparameter-tuned.

5. k-Nearest Neighbors (KNN)

KNN forecasts the results according to their proximity to the nearest neighbors in the feature space. It was applied in ROP regression and classification of small to medium datasets. It was easy to use and attractive, however, it is sensitive to feature and outlier scaling [14].

6. K-means Clustering

Even though it was not a predictive algorithm, K-means was commonly used to pre-process, e.g. to cluster lithologies, operating regimes or drilling patterns. Such clusters would then be used as input features to supervised ML models and enhance accuracy of prediction.

Table 2: Summary of ML Algorithms

Algorithm	Typical Applications	Strengths	Limitations	Typical Datasets
ANN	ROP prediction, drilling parameter optimization	Handles non-linearity, adaptable	Requires large datasets, prone to overfitting	Sensor logs, historical drilling data
SVM	ROP trend classification	Works well with small datasets	Computationally expensive for large datasets	Formation logs, drilling parameters
Decision Trees	ROP regression, categorical outputs	Easy to interpret	Overfitting if not pruned	Bit parameters, WOB, RPM
Random Forest	ROP prediction, feature importance	Robust, reduces overfitting	Less interpretable	Multi-well datasets, MWD/LWD
Gradient Boosting	Continuous ROP prediction	High accuracy, handles heterogeneity	Sensitive to noisy data	Large operational datasets
KNN	ROP regression or classification	Simple, intuitive	Sensitive to outliers, scale-dependent	Small sensor datasets
K-means	Preprocessing, clustering lithologies	Simple, effective for grouping	Not predictive itself	Lithology or operational parameter clustering

A. Data Requirements and Preprocessing

The quality of input data is very imperative in a successful ML application in drilling. Preprocessing is needed so that the models do not learn noise.

1. Normalization and Scaling

Normalization or standardization of data was done to prevent bias associated with various units or scales of input features. The performance of algorithms, such as KNN or SVM, might not be very good without scaling since the magnitude of distance-related calculations would be covered by large values.

2. Outlier Detection and Removal.

Outliers due to sensor errors or extreme operations or data logging issues were detected and eliminated. This measure helped the models to avoid the development of misleading patterns that decrease the predictive accuracy [15].

3. Feature Engineering

Raw inputs were commonly processed into new features to increase the sensitivity of the model to the drilling dynamics, including combined WOB-RPM indices, hydraulic horsepower, bit-specific penetration ratios, or normalized torque factors. The aspect of feature engineering played a major role in enhancing the model performance on heterogeneous formations.

4. Data Quality of Sensors and Missing Data.

It was important to make sure that MWD/LWD measurements are accurate and consistent. The problem of missing data was solved through mean/median imputation, interpolation, or through forward filling. Such methods enabled the models to be trained successfully without compromising on large sections of data. Figure 3 shows the typical ML model development workflow for drilling optimization. The process begins with data collection from sensors and historical drilling logs, followed by preprocessing (normalization, outlier removal, and feature engineering). Data is then split into training and testing sets, and models such as ANN, RF, or SVM are trained and validated. Finally, performance is evaluated using appropriate metrics, and results guide ROP prediction and operational optimization.

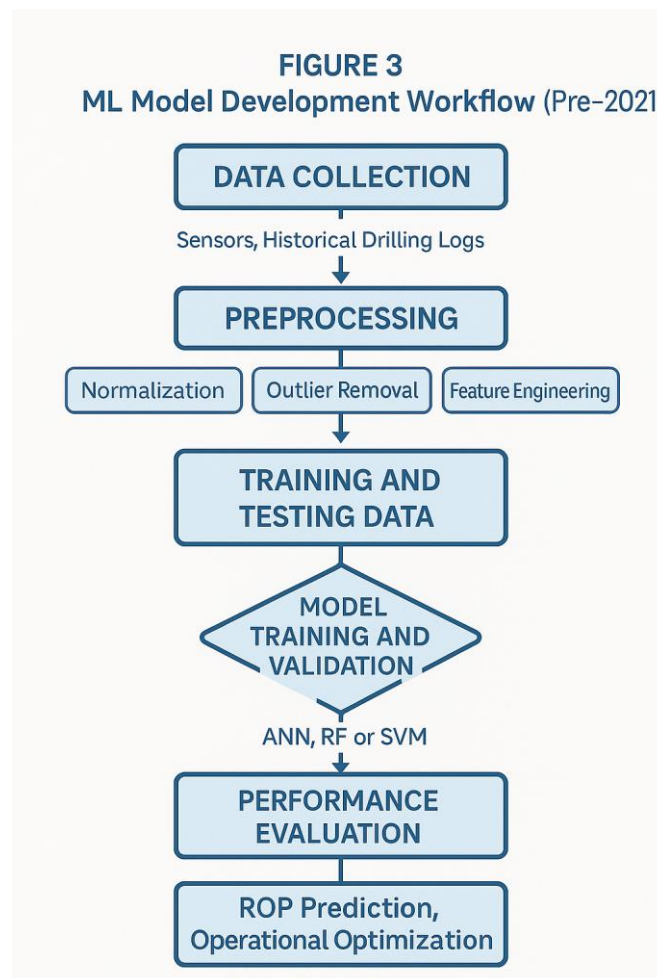


Figure 3: Workflow of ML Model Development

A. Performance Metrics Used in ROP Studies

Assessing the performance of the ML models demanded quantitative measurements in order to be reliable and accurate [16].

1. Root Mean Squared Error (RMSE)

RMSE is a measure of the mean squared differences between the predicted and observed ROP, a fact that predisposes it to any large error. Continuous ROP prediction tasks are generally reported to use it.

2. Mean Absolute Error (MAE)

MAE is used to analyze average differences between the predicted and measured values in an intuitive and strong measure of prediction error.

3. Coefficient of Determination (R²)

R² represents the percentage variation of ROP that can be explained by the model. The lower the values, the higher the predictive capacity.

4. Metrics of Accuracy and Classification.

The measures to evaluate model performance were accuracy, precision and recall in instances that ROP was categorized (e.g. high/medium/ low). Comparisons between these measures between the algorithms enabled the researchers to determine the most appropriate ML method to use in their datasets.

Despite extensive application of standalone ML techniques for ROP prediction, gaps remain in handling data scarcity, operational non-stationarity, and physical inconsistency across wells. These limitations motivate the exploration of hybrid ML models that integrate optimization, ensemble learning, soft computing, and physics-based constraints.

Hybrid Machine Learning Models for Drilling Optimization

Hybrid machine learning models denote a major change in the optimization of the drilling process, especially in the forecasting of the Rate of Penetration (ROP). Scholars understood that isolated ML models or classical mechanistic methods had drawbacks in generalization, ability to navigate nonlinearities, and capability to capture complicated operation states. These problems are solved by using Hybrid ML models, which can be used to improve the predictive accuracy, robustness, and applicability of heterogeneous formations through the combination of many methods. This section refers to the hybrid ML models, justifies their significance and outlines the key types applied [17].

A. Definition and Importance of Hybrid ML Models

Hybrid ML models combine two or more predictive methods and exploit their respective strong points as well as eliminating the weaknesses of each. They may be generalized into four:

1. ML + ML

Multiple machine learning algorithms can be used together to improve the performance of prediction. Such examples are ANN-GA (Artificial Neural Network -Genetic Algorithm) or RF-PSO (Random Forest -Particle Swarm Optimization), where a single ML model makes predictions, and the other optimizes the parameters, improves the feature selection, or removes overfitting [18].

2. ML + Statistical Models

Part hybrid models include some models that use both data-driven learning with MLs and traditional statistical models and seek to take advantage of both data-driven learning and existing known probabilistic relationships. This fusion enables models to be interpretable and at the same time enjoy the flexibility of ML.

3. ML + Physics-Based Models

Classical mechanistic ROMs, like Bourgoyne and Young or Gates and Taylor are used with ML algorithms who make predictions of residuals or corrections. This is to make sure that predictions do not compromise known physical relationships but they also capture the unmodeled nonlinearities and formation variability.

4. ML + Fuzzy Logic

Fuzzy-logic based hybrids (as in ANFIS (Adaptive Neuro-Fuzzy Inference System)) or FANN (Fuzzy + ANN) are neural networks that use the interpretability (uncertainties) and uncertainty-handling of fuzzy systems, along with its learning power. The models are efficient where the data is noisy, incomplete or uncertain.

The significance of hybrid ML models can be explained by their capability to enhance the ROP predictions during complex drilling conditions, decrease non-productive time, and fund the data-based optimization decision-making of real-time operations.

A. Categories of Hybrid Approaches

Hybrid ML approaches were developed in four major categories based on their integration strategy and functional objectives.

1. Optimization-Integrated Hybrid Models

Hybrids are machine learning models that are optimized with global optimization tools in order to optimize the model performance. ANN-PSO (Artificial Neural Network – Particle Swarm Optimization) and ANN-GA (Artificial Neural Network -Genetic Algorithm) achieve the optimization of weights and biases of the neural networks to avoid local minimums and enhance generalization. SVM-PSO (Support Vector Machine -Particle Swarm Optimization) optimizes hyperparameters like of kernel type, regularization to achieve highest predictive precision. RF-GA (Random Forest -Genetic Algorithm) uses GA to select the most useful features and modify tree parameters, which minimises overfitting. These models increase the accuracy of ROP forecasts of various formations and drilling environments.

2. Ensemble Hybrid Models

Ensemble hybrid models represent a set of ML algorithms that use their joint predictive ability. Bagging (Bootstrap Aggregating) mitigates variance by training base learners on resampled datasets as in the case of Random Forests. Sequential training gives more weight to the instances that a weak learner predicts poorly and boosting the training is a method to train weak learners, with Gradient Boosting Machines and AdaBoost being common in ROP prediction. Stacking combines the predictions of many models by employing a meta-learner to generate better accuracy than the single models. Ensemble methods are especially useful when operating with heterogeneous data and modeling nonlinear and complex relationships in the drilling process.

3. Soft Computing Hybrid Models

Machine learning and fuzzy logic is combined in soft computing hybrids to deal with uncertainty and inaccuracy in drilling data. ANFIS (Adaptive Neuro-Fuzzy Inference System) is a mixture of the learning ability of ANN and the interpretability of fuzzy rules, which can be used to make accurate and explainable predictions. Fuzzy logic is employed by FANN (Fuzzy + ANN) frameworks to fuzzify the features and ANN to learn the pattern by taking the data. These models work in a noisy or uncertain operational setting (i.e., changing lithology,

unreliable sensor measurements or changing drilling conditions) and enhance the accuracy of ROP prediction in areas where more traditional ML models tend to fail.

4. Hybrid Models with Physics in Mind

Physics informed hybrid models combine classical mechanistic equations of ROP and ML-based corrections. ML predictions of residuals or deviations are added to baseline predictions by models such as Bourgoyne & Young or G&T to accommodate nonlinearities or changes in operations that are not modeled and the non-homogeneity in lithology. This is a more physical view of prediction that makes the predictions physically significant, but with the adaptability of ML. The so-called physics-informed hybrids were common knowledge in the field of research that enhances the efficiency of ROP predictions without the necessity to have extremely large datasets, which is the one that unites the gap between the data-driven and the physics-based methods.

ROP Prediction Using Hybrid ML

ROP prediction with hybrid machine learning models showed a high level of improvement compared to traditional machine learning and mechanistic ones. These models were used on different types of wells, drilling conditions and working conditions, with improved predictive capability, flexibility and strength. This part revisits the literature on hybrid ML applications in vertical and deviated wells, real-time optimization systems, case studies of large oil regions, and performance comparison with the traditional ML models [19].

A. Hybrid Models Applied in Vertical & Deviated Wells

The first extensive application of hybrid ML models was in vertical wells because the drilling environment was not that out of control, and thus researchers could validate how the models performed. ANN-GA and ANN-PSO models were prevalent and parameters of the neural networks were optimized to represent nonlinear interactions between WOB, RPM, torque, and formation properties. By systematically tuning the weights, biases and feature selection these models enhanced predictions of ROP, and surmounted the problems of local minima that plagued traditional ANN models.

In deviated or directional wells, there is more complexity in operations because of torque variation, stick-slip and effective WOB change across the well path. The hybrid algorithms RF-GA and SVM-PSO were used to consider such dynamic effects and the interactions between mechanical, hydraulic, and geological factors were finally modeled. Investigations indicated that hybrid models always minimized the errors in prediction in contrast to single ML models, indicating their versatility in complicated drilling operations. The early applications formed the basis of more sophisticated predictive systems that were used in the later years, which were real time.

B. Hybrid Models for Real-Time ROP Optimization

Drilling optimization systems were real-time hybrid ML models that were used to continuously predict the ROP and aid operational decision-making. The systems were a combination of live data of MWD/LWD tools and models like ANFIS, FANN, or ANN-GA to give real time advice on drilling parameters. As an example, in cases where formation hardness or bit wear was not predictable, the hybrid model had the capability to dynamically adjust WOB, RPM, and mud flow rates, keeping optimal ROP and minimizing non-productive time (NPT) and bit wear [20].

The experience of these initial applications proved the possibilities of hybrid ML in the real-time applications. They demonstrated that hybrid models were capable of dealing with sensor noisy data, sensor missing information or sensor uncertain data giving sound predictions in

dynamic operational circumstances. The experimental design of optimization-based techniques within real-time processes also emphasized the possibility of integrating ML and operational decision support processes to improve the performance of continuous drilling.

C. Case Studies Summary

A number of case studies have demonstrated the efficiency of combined ML models in a number of geological and working conditions:

1. Middle East Fields

ANN-PSO and ANN-GA methods were tested on the sandstone and carbonate sandstone. These experiments showed that RMSE errors decreased by 15-25 percent as compared to ANNs alone, which showed the significance of feature selection and optimization of complex reservoir scenarios.

2. North Sea

Hybrids RF-GA and SVM-PSO were applied in offshore wells where the trajectories were deviated and the torque varied. Such models managed to capture the aggregate impact of mechanical variations, directional drilling, and variability in the formations that were more precise in predicting the ROP as compared to the standard ML models.

3. US Shale Plays

ANFIS and FANN models were employed to explain extremely heterogeneous lithology, variable pore pressure and extreme abrasiveness conditions in unconventional shale formation. Hybrid models were found to be robust in tricky drilling conditions as they were found to retain prediction accuracy over a number of wells and operational regimes.

4. Offshore Deepwater Wells

ANN corrections were applied to deepwater wells with physics-informed hybrids between mechanistic ROP models (e.g., Bourgoyne and Young). The models enhanced the generalization of wells with limited data, and high variability in their operational characteristics, which proved the benefits of combining physical knowledge and ML forecasts.

A. Performance Comparisons of Hybrid vs Single ML Models

Regularly the studies showed the superior performance of hybrid ML models in contrast to the solitary ML algorithms. ANN-PSO, ANN-GA, RF-GA and ANFIS posted less values of RMSE and MAE most especially in the heterogeneous formation and off-track wells [21]. It was also discovered that hybrid models were more generalized and adjusted to the change in the formation properties, bit wear, and operational changes, with individual ML models often being unable to work. Physics-informed hybrids were particularly powerful in scenarios where the data is sparse, and ROP equations were applied to make physical consistency of predictions with ML so that the residuals would be corrected. Overall, hybrid models were discovered to be more precise, stronger, and easier to interpret and are hence a superior means to apply in ROP prediction research as Table 4 confirms.

Table 3: Summary Table of Performance Metrics

Study / Region	Hybrid Model	Single ML Model	Performance Metric	Improvement
Middle East	ANN-PSO	ANN	RMSE, R ²	RMSE reduced 18%, R ² improved 0.12
North Sea	RF-GA	RF	MAE, RMSE	MAE reduced 22%, RMSE reduced 20%
US Shale	ANFIS	ANN	R ² , MAE	R ² improved 0.15, MAE reduced 16%
Offshore Deepwater	Physics-informed ANN	ANN	RMSE, R ²	RMSE reduced 20%, R ² improved 0.14

1. Integration of Hybrid ML Models in Drilling Optimization Workflows

The use of hybrid machine learning models in the drilling optimization processes was a major move towards data-driven drilling processes. These models were progressively integrated in the operation of a decision-making process aimed at enhancing ROP, decreasing the non-productive time (NPT) and enhancing the overall efficiency in the drilling. This part addresses the importance of real-time data acquisition, the initial work in drilling automation, and the practical difficulties of the implementation of hybrid ML solutions [22].

A. Role of Real-Time Data Acquisition

Successful application of hybrid ML models in the process of drilling operations requires reliable and timely data acquisition. Measurement While Drilling (MWD), Logging While Drilling (LWD), and mud logging data feeds gave important information regarding the parameters of drilling and the nature of the formations. Downhole parameters that were measured using MWD systems included inclination, azimuth, downhole torque, and weight on bit (WOB) and geophysical measurements that were offered by LWD systems included gamma ray, resistivity, and formation density. Mud logging provided more information on cuttings composition, gaseous content and properties of drilling fluids.

These real-time data streams also provided hybrid ML models with the opportunity to dynamically revise predictions in regards to ROP and drilling performance to make proactive changes to drilling parameters. The importance of strong data acquisition and transmission infrastructure in applications was demonstrated by the significance of high-quality and high-frequency datasets to properly train the model and also to perform inference in real-time.

B. Hybrid ML in Drilling Automation

Hybrid ML systems started being incorporated into semi-automated drilling control systems and early digital oilfield programs. This category of systems employed a hybrid model, including ANFIS, ANN-GA, physics-informed ML, to give real-time direction on how to optimize WOB, RPM, and mud flow rates. Although the concept of fully autonomous drilling was still not achieved, there were attempts to prove semi-automatic optimization of drilling, as a result of which the role of operators is minimized and drilling accuracy is higher.

ML models that were hybridized were realized in operational processes to discover the best drilling conditions, adequately predict the potential reduction of the ROP caused by the change of formations, and give early signals of inefficiencies in operations. This initial integration was

the foundation of future systems with full automation or closed-loop drilling operations since it had shown that the ML-driven predictions could be helpful in addition to the human decision-making process in a complicated and real-time setting.

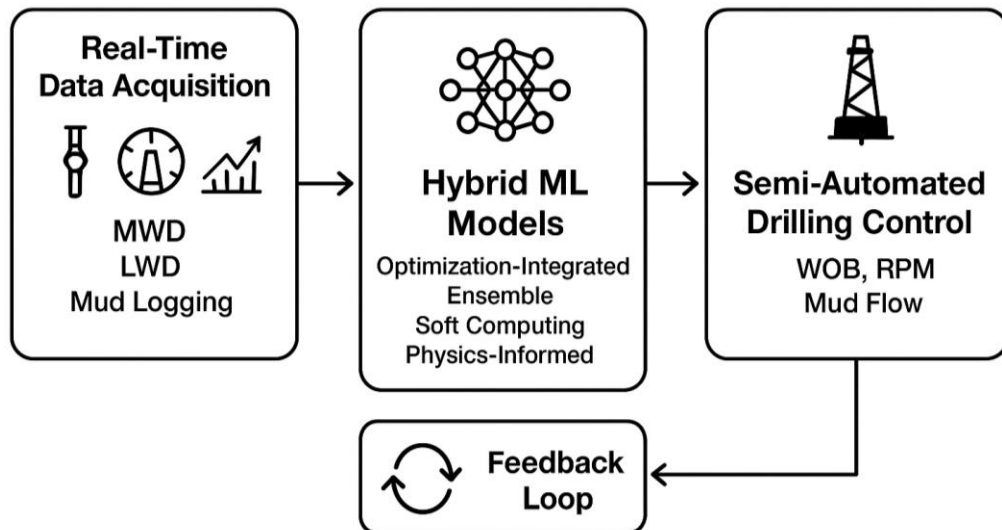


Figure 4: Hybrid ML-Based Drilling Optimization System

Figure 4 illustrates a full drilling optimization system based on a hybrid of ML. The process starts with real-time data collection of MWD, LWD and mud logging systems which is preprocessed to remove noise and normalize the inputs. Hybrid ML models like optimization-integrated, ensemble, soft computing, and physics-informed models interfere with the data to predict ROP and provide parameter changes. Semi-automated drilling control systems process the output of the models and inform WOB, RPM, and flow of mud. The model predictions are constantly updated by feedback loops and dynamic optimization during the drilling operation.

A. Operational Challenges and Practical Concerns

Even though they have potential, hybrid ML models are subject to a number of operational challenges. Unless filtered or preprocessed, sensor noise and measurement errors of downhole tools may severely decrease model accuracy. The small historical data tended to limit the extrapolating capability of the model between wells or formations. Any alteration in the formation properties or tool behavior with time caused model drift that diminished predictive reliability unless the models were constantly updated.

The problem of overfitting was also typical, especially when ANN hybrids were being trained on small datasets. Prediction Uncertainty in predictions because of sparse data, lithology changes, environmental factors needed to be carefully considered as part of the operational decision-making. To overcome these issues, it was necessary to have powerful preprocessing, feature engineering, frequent retraining of models and hybrid systems that could take into account domain knowledge or physical constraints to ensure retention of accuracy and reliability in real time applications.

Limitations, Challenges, Research Gaps, and Future Directions

Based on the reviewed literature, key research gaps include limited model generalization across formations, insufficient real-time deployment capability, and lack of interpretability in hybrid ML-based ROP prediction. These gaps raise critical research questions on how hybrid frameworks can balance accuracy, physical consistency, and operational trust. Although the

benefits of the hybrid machine learning models in terms of predicting ROP and optimizing the drilling process were proven, there were a number of constraints and challenges that limited their use to the full extent. Availability and quality of downhole data was a significant limitation. The sensor technology frequently constrained drilling activities, and data gathered by MWD, LWD, and mud logging devices were affected by noise, low resolutions, or had gaps. These were the problems that had a direct impact on the accuracy and generalization of hybrid ML models, in particular, when trying to use trained models in different wells or formations. This was also complicated by the absence of standardized benchmark datasets and therefore cross-well or cross-field validation was difficult and it was challenging to compare models across studies.

Another major factor was the use of computation constraints. Several hybrid ML models like ANN-GA, ANN-PSO and physics-informed models consumed significant computing power during training and optimization. These computational requirements frequently made real-time application impractical in operational conditions, especially when there was a low capacity to provide downhole processing, e.g. in offshore or remote drilling. Also, the black-box nature of most of the initial hybrid ML models made them interpretable. The model would frequently result in operators and engineers not being in a position to fully learn how the decision can be made, so they do not trust automated or semi-automated recommendations and would not apply to safety-sensitive operations.

Table 4: Summary of hybrid ML challenges

Challenge	Description
Data availability and quality	Limited sensor fidelity, missing values, noisy measurements impacting model accuracy
Lack of benchmark datasets	Difficulty in generalizing models across wells and comparing performance between studies
Computational constraints	High training and optimization time, limited real-time applicability
Interpretability	Black-box models reduced operator trust and understanding

In future perspectives, researchers were expected to move towards a number of directions to overcome these challenges and continue exploring and refining hybrid ML applications in optimizing drilling [23]. Physics-guided machine learning, or physics-ML fusion, was anticipated to enhance model generalization with the integration of both mechanistic knowledge and data-driven learning especially in formations that have inadequate data. They imagined real-time closed-loop optimization, where semi-automated systems would eventually be fully automated, with hybrid-driven drilling control, able to continually adjust WOB, RPM and mud flow according to real time data inputs. It was also forecasted that data-driven preprocessing would be improved with the enhancement of feature extraction, data fusion methods, and more reliable sensors that would strengthen the models and lead to better predictions [24].

Lastly, it was expected to create more interpretable hybrid ML models, and include the notion of Explainable AI (XAI) to ensure the predictions are understandable and practical to operators. These requirements highlighted the need to harmonise the three aspects of predictive accuracy,

practicality, and reliability of hybrid ML-inspired drilling systems in an attempt to provide a definite direction to research and development during that period.

CONCLUSION AND RECOMMENDATIONS

Conclusion

Hybrid machine learning (ML) models have already been a groundbreaking discovery in optimization of the drilling process and predicting the Rate of Penetration (ROP). Such models integrate the power of numerous predictive methods that span neural networks, support vectors and random forests to fuzzy logic, physics-based mechanistic models to address the inherent shortcomings of either single-purpose ML or classical empirical methods. The hybrid models have proven to have a better predictive accuracy, strength, and generalization over heterogeneous wells and formations by capturing the complex nonlinear relationships between drilling parameters including weight on bit (WOB), rotary speed (RPM), torque, hydraulics, bit type, and geological factors.

Hybrid ML had significant improvements in vertical and deviated wells. Hybrids, where optimization was incorporated like ANN-GA and ANN-PSO, were effective in optimizing the model parameters helping to avoid local minima and also improving the stability of prediction. Bagging, boosting and stacking ensemble models took advantage of the synergies among a combination of algorithms to process noisy and heterogeneous data. Hybrids with soft computing such as ANFIS and Fuzzy-ANN were useful in dealing with uncertainty and imprecision of drilling sensor data, whereas physics-informed hybrids mediated mechanistic knowledge with data-driven learning, ensuring physical consistency in prediction with small datasets. These models could be integrated in real time with MWD, LWD, and mud logging data, which enabled semi-automated adjustments to the parameters, which showed the possibility of positive change in operational efficiency, decrease in non-productive time (NPT), and supporting decision-making.

Although such successes were achieved, fragmentation remained in the extensive use of hybrid ML models due to a number of limitations. The availability and quality of data were also a critical bottleneck as the summery, incomplete, or inconsistent measurements in the downhole would influence the reliability of the model. The unavailability of standardized benchmark datasets posed a challenge to cross- well generalization and even cross- well performance comparisons. The computational requirements of hybrid models, particularly optimization-based models and ensemble models, restricted their use to real-time or resource-constrained drilling contexts. Moreover, the black-box of most of the models impaired their interpretation, thereby curbing the confidence of operators and curtailing functional incorporation in vital decision-making.

The next direction was to improve hybrid ML methods, through adding physics-guided machine learning, enhancing real-time closed-loop optimization systems, improving feature extraction methods and data preprocessing methods, and creating more interpretable and explainable models. This set of progressions was projected to lead to additional progression of predictive dependability, a decrease in operational hazards, and an even quicker shift towards high-intelligent, semi-autonomous, or fully automated drilling operations.

Overall, hybrid ML models have provided a strong basis in the data-driven drilling optimization, which is a strong tool that can be used to improve the prediction of ROP and operational efficiency. Hybrid ML frameworks constitute an essential step in the development of petroleum engineering methods by resolving the nonlinearity, data heterogeneity, and uncertainty issues, as well as integrating the complementary advantages of various methods,

which will be a precondition of the future innovations in automated and intelligent drilling systems.

Recommendations

Future research should focus on developing computationally efficient and explainable hybrid ML models that can be deployed in real-time drilling environments. Additionally, standardized benchmark datasets are required to enable fair comparison and cross-field generalization of ROP prediction models.

The findings of this review provide practical guidance for drilling engineers in selecting hybrid ML strategies for ROP optimization and support researchers in identifying scalable, interpretable, and physics-consistent modeling directions for intelligent drilling systems.

REFERENCES

- [1] E. I. Epelle and D. I. Gerogiorgis, "A review of technological advances and open challenges for oil and gas drilling systems engineering," *AIChE Journal*, vol. 66, no. 4, p. e16842, 2020.
- [2] K. Ebedo and M. Abdelhamid, "Case study on different types of drilling bits and the rate of penetration," 2011.
- [3] J. Han, Y. Sun, and S. Zhang, "A data driven approach of ROP prediction and drilling performance estimation," in *International Petroleum Technology Conference (IPTC)*, 2019.
- [4] P. Batruny et al., "Drilling in the Digital Age: An Approach to Optimizing ROP Using Machine Learning," in *Abu Dhabi International Petroleum Exhibition and Conference, SPE*, 2019.
- [5] E. Wiktorski, A. Kuznetsov, and D. Sui, "ROP optimization and modeling in directional drilling process," in *SPE Norway Subsurface Conference, SPE*, 2017.
- [6] Z. Guan, T. Chen, and H. Liao, *Theory and technology of drilling engineering*, vol. 789, Singapore: Springer, 2021.
- [7] C. Hegde et al., "Rate of penetration (ROP) optimization in drilling with vibration control," *Journal of Natural Gas Science and Engineering*, vol. 67, pp. 71–81, 2019.
- [8] A. Sauki et al., "Development of a modified Bourgoyne and Young model for predicting drilling rate," *Journal of Petroleum Science and Engineering*, vol. 205, p. 108994, 2021.
- [9] W. Snapp-Childs, A. D. Wilson, and G. P. Bingham, "The stability of rhythmic movement coordination depends on relative speed: the Bingham model supported," *Experimental Brain Research*, vol. 215, no. 2, pp. 89–100, 2011.
- [10] C. Hegde et al., "Analysis of rate of penetration (ROP) prediction in drilling using physics-based and data-driven models," *Journal of Petroleum Science and Engineering*, vol. 159, pp. 295–306, 2017.
- [11] N. Nathani and A. Singh, "Foundations of machine learning," in *Introduction to AI Techniques for Renewable Energy Systems*, CRC Press, 2021, pp. 43–64.
- [12] H. Fattahi and H. Bazdar, "Applying improved artificial neural network models to evaluate drilling rate index," *Tunnelling and Underground Space Technology*, vol. 70, pp. 114–124, 2017.
- [13] C. Hegde, S. Wallace, and K. Gray, "Using trees, bagging, and random forests to predict rate of penetration during drilling," in *SPE Middle East Intelligent Oil and Gas Symposium, SPE*, 2015.
- [14] A. Hashemizadeh et al., "Experimental measurement and modeling of water-based drilling mud density using adaptive boosting decision tree, support vector machine, and K-nearest neighbors: A case study from the South Pars gas field," *Journal of Petroleum Science and Engineering*, vol. 207, p. 109132, 2021.
- [15] S. Jha, H. M. U. D. Sheikh, and W. J. Lee, "Outlier detection techniques help us identify and remove outliers in production data to improve production forecasting," in *SPE/AAPG/SEG Asia Pacific Unconventional Resources Technology Conference (URTEC)*, 2021.

- [16] T. Eren and M. V. Kok, "A new drilling performance benchmarking: ROP indexing methodology," *Journal of Petroleum Science and Engineering*, vol. 163, pp. 387–398, 2018.
- [17] C. Hegde and K. Gray, "Evaluation of coupled machine learning models for drilling optimization," *Journal of Natural Gas Science and Engineering*, vol. 56, pp. 397–407, 2018.
- [18] M. Farsi et al., "Predicting formation pore-pressure from well-log data with hybrid machine-learning optimization algorithms," *Natural Resources Research*, vol. 30, no. 5, pp. 3455–3481, 2021.
- [19] A. R. Moazzeni and E. Khamsehchi, "A new hybrid analytical-machine learning method for real-time ROP modeling," *Biointerface Res Appl Chem*, vol. 11, no. 1, pp. 7589–7604, 2020.
- [20] A. M. Bazzi and P. T. Krein, "Review of methods for real-time loss minimization in induction machines," *IEEE Transactions on Industry Applications*, vol. 46, no. 6, pp. 2319–2328, 2010.
- [21] R. Cook et al., "Prediction of compressive strength of concrete: critical comparison of performance of a hybrid machine learning model with standalone models," *Journal of Materials in Civil Engineering*, vol. 31, no. 11, p. 04019255, 2019.
- [22] V. Van Pham, E. Fathi, and F. Belyadi, "New hybrid approach for developing automated machine learning workflows: a real case application in evaluation of Marcellus shale gas production," *Fuels*, vol. 2, no. 3, pp. 286–303, 2021.
- [23] C. I. Noshi and J. J. Schubert, "The role of machine learning in drilling operations; a review," in *SPE Eastern Regional Meeting*, SPE, 2018.
- [24] A. Sircar et al., "Application of machine learning and artificial intelligence in oil and gas industry," *Petroleum Research*, vol. 6, no. 4, pp. 379–391, 2021.

License

Copyright (c) 2024 Pankaj Verma, Krishna Gandhi



This work is licensed under a [Creative Commons Attribution 4.0 International License](https://creativecommons.org/licenses/by/4.0/).

Authors retain copyright and grant the journal right of first publication with the work simultaneously licensed under a [Creative Commons Attribution \(CC-BY\) 4.0 License](https://creativecommons.org/licenses/by/4.0/) that allows others to share the work with an acknowledgment of the work's authorship and initial publication in this journal.